



### Accessories

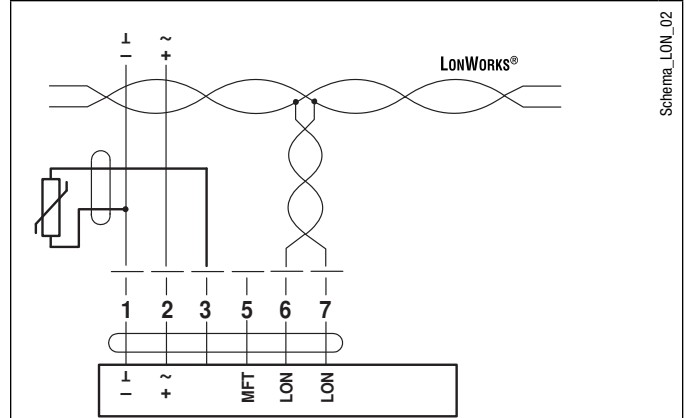
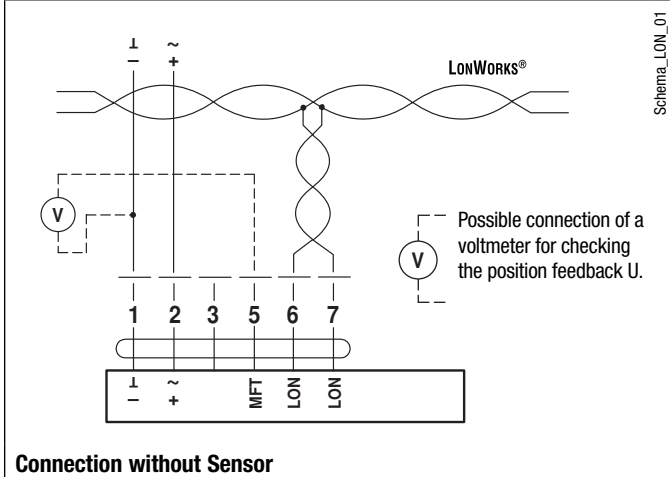
AV 8-25	Shaft extension
IND-AFB	Damper position indicator
KH-AFB	Crank arm
K7-2	Universal clamp for up to 1.05" dia jackshafts
TF-CC US	Conduit fitting
Tool-06	8mm and 10 mm wrench
ZG-100	Universal mounting bracket
ZG-101	Universal mounting bracket
ZG-102	Multiple actuator mounting bracket
ZG-118	Mounting bracket for Barber Colman® MA 3./4., Honeywell® Mod III or IV or Johnson® Series 100 replacement or new crank arm type installations
ZG-AFB	Crank arm adaptor kit
ZG-AFB118	Crank arm adaptor kit
ZS-100	Weather shield (metal)
ZS-150	Weather shield (polycarbonate)
ZS-260	Explosion-proof housing
ZS-300	NEMA 4X housing

**NOTE:** When using AFX24LON actuator, only use accessories listed on this page.

### Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide proportional damper control in response to a LonWorks controller. The actuators must be designed so that they may be used for either clockwise or counterclockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators shall be cULus Approved and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

### Wiring Diagrams

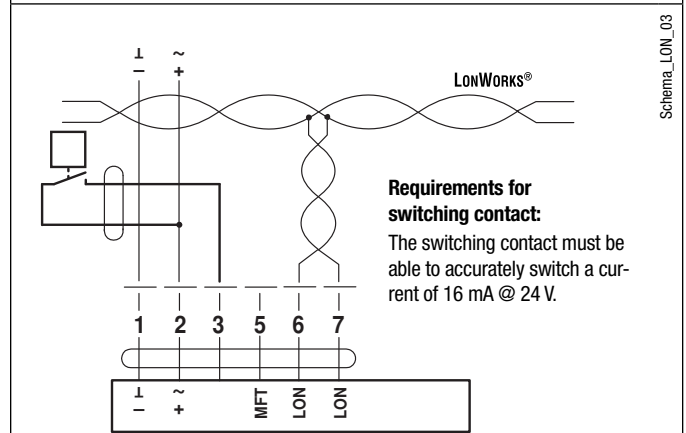


### Sensor scaling:

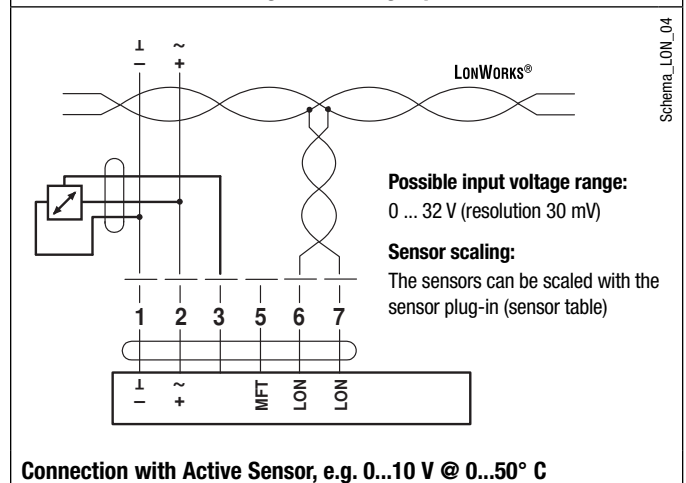
The sensors can be scaled with the sensor plug-in (sensor table).

Sensor	Temperature range	Resistance range	Resolution
Ni1000	-28 ... +98°C	850 ... 1600 Ω	1 Ω
PT1000	-35 ... +155°C	850 ... 1600 Ω	1 Ω
NTC	-10 ... +160°C (depending on type)	200 ... 60 kΩ	1 Ω

### Connection with Passive Sensor, e.g. Pt1000, Ni1000, NTC

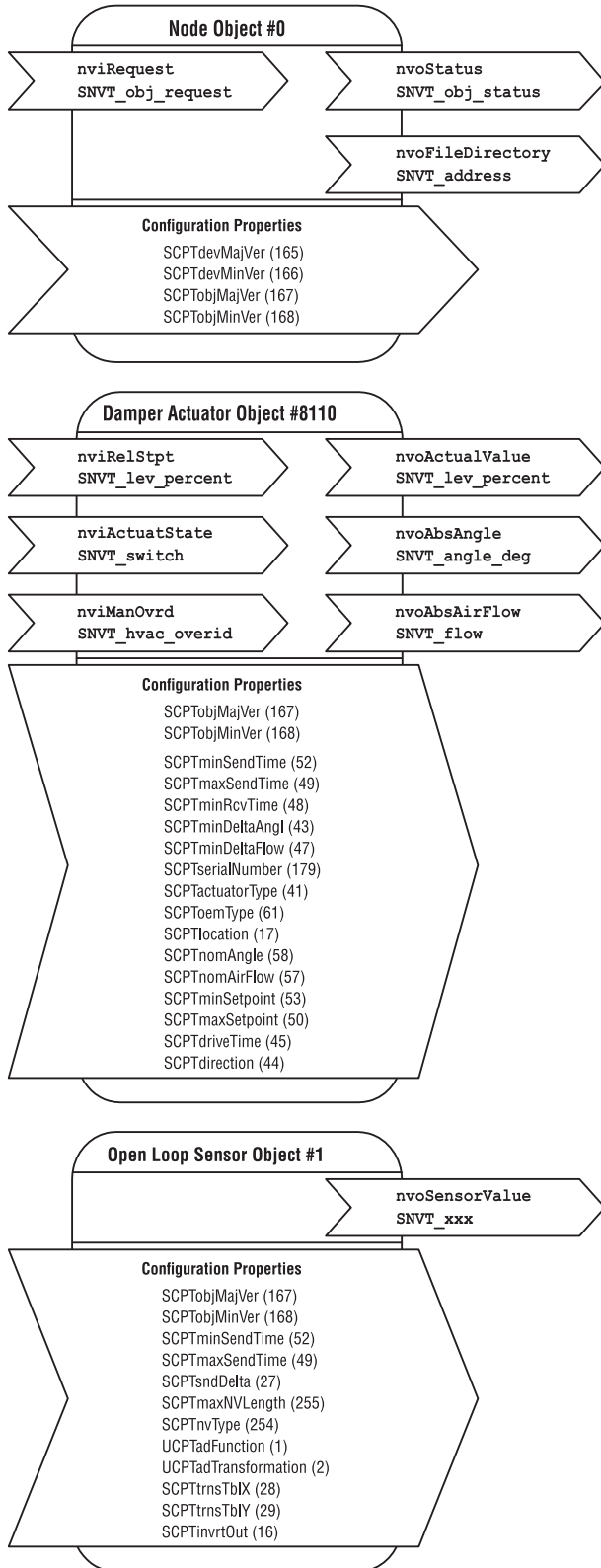


### Connection with Switching Contact, e.g. Δp-monitor



**Functional Profile according to LonMARK®**

The LON-capable damper actuator is certified by LonMARK®. The actuator functions are supplied with the LonWorks® network as standardized network variables according to LonMARK®. The Node Object #0, the Damper Actuator Object #8110 and the Open Loop SensorObject #1 are implemented in the actuator.



**Node object #0**

The node object contains the object status and object request functions.

**nviRequest**      **SNVT\_obj\_request**  
Input variable for requesting the status of a particular object in the node.

**nvoStatus**      **SNVT\_obj\_status**  
Output variable that outputs the current status of a particular object in the node.

**nvoFileDirectory**      **SNVT\_address**  
Output variable that shows information in the address range of the Neuron chip.

**Damper actuator object #8110**

The actuator object is used to map the functions of the MP actuators to the LONWORKS® network.

**nviRelStpt**      **SNVT\_lev\_percent**  
The nominal position is assigned to the actuator via this input variable. This variable is normally linked to the output variable of an HVAC controller.

**nviActuateState**      **SNVT\_switch**  
A preset position is assigned to the actuator via this input variable. Note on priority: The last variable that was active, either nviActuatorState or nviRelStpt, has priority.

**nviManOvr**      **SNVT\_hvac\_overid**  
These input variables can be used to manually override the actuator into a particular position.

**nvoActualValue**      **SNVT\_lev\_percent**  
This output variable shows the current actual position of the actuator and can be used for control circuit feedback or for displaying positions.

**nvoAbsAngle**      **SNVT\_angle\_deg**  
This output variable shows the current angle of rotation of the actuator or the valve and can be used to display the position or for service purposes.

**nvoAbsAirFlow**      **SNVT\_flow**  
This output variable is inactive with the SR24ALON-5 rotary actuator and shows a constant value of 65535 (this variable is only active in conjunction with LON-capable VAV controllers).

**Open loop sensor object #1**

A sensor can be connected to the rotary actuator. A passive resistance sensor (e.g. Ni1000), an active sensor (output 0 ... 32 V) or a switch (on/off) can be connected. The open loop sensor object transfers the measured sensor values to the LONWORKS® network.

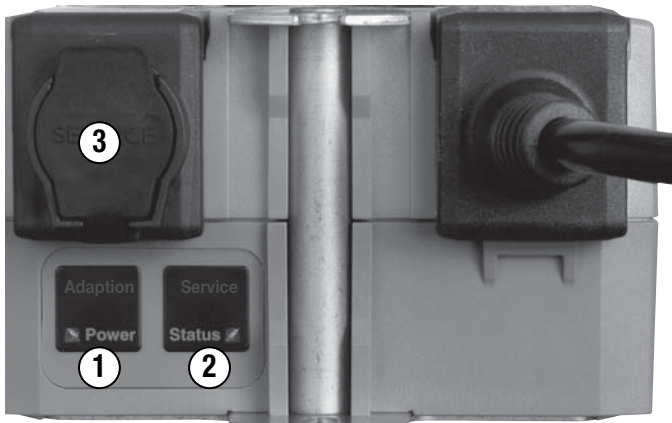
**nvoSensorValue**      **SNVT\_xxx**  
This output variable shows the current sensor value. Depending on the connected sensor, the output variable can be configured via the sensor plug-in and specifically adapted to the system.

**The SNVT\_... can be configured as:**

SNVT_temp_p	SNVT_lev_percent	SNVT_lux
SNVT_temp	SNVT_abs_humid	SNVT_press_p
SNVT_switch	SNVT_enthalpy	SNVT_smo_obscur
SNVT_flow	SNVT_ppm	SNVT_power
SNVT_flow_p	SNVT_rpm	SNVT_elec_kwh

**Notes**

Detailed information on the functional profiles can be found on the website of LonMARK® ([www.lonmark.org](http://www.lonmark.org)).



**1 Membrane key and green LED display**

Off	No voltage supply or malfunction
On	Operation
Press button	Switches on angle of rotation adaption followed by standard operation

**2 Membrane key and yellow LED display**

Off	The actuator is integrated ready-for-operation in the LONWORKS® network.
On	No application software is loaded in the actuator.
Blinking (flashing interval 2 seconds)	The actuator is ready-for-operation, but not integrated in the LONWORKS® network (unconfigured).
Other flashing codes	A fault is present in the actuator.
Press button	Service Pin Message will be sent to the LONWORKS® network.

**3 Service plug**

For connecting MFT parameterizing and service tools

**Operating Controls**

The hand crank, interlocking switch and direction of rotation switch are provided on both sides.