







Technical Data	AFX24LON	
Power supply	24 VAC, +/- 20%, 50/60 Hz	
	24 VDC, +20% / -10%	
Power running	8.5 W	
consumption holding	3.5 W	
Transformer sizing	11 VA (Class 2 power source)	
Electrical connection	3 ft, 18 GA appliance cable, 1/2" conduit connector	
Overload protection	electronic throughout 0 to 95° rotation	
Feedback output U	2 to 10 VDC, 0.5 mA max	
Torque	minimum 180 in-lb (20 Nm)	
Direction of spring	reversible with cw/ccw mounting	
rotation motor	reversible with built-in switch	
Mechanical	95° (adjustable with mechanical end stop, 35° to 95°)	
angle of rotation		
Running time spring	<20 sec @ -4°F to 122°F [-20° C to 50° C];	
	<60 sec @ -22°F [-30° C]	
motor	150 seconds (default), variable (70 to 220 seconds)	
Angle of Rotation	off (default)	
adaptation		
Override control	min position = 0%	
via nviManOvrd	mid. position = 50%	
	max. position = 100%	
Position indication	visual indicator, 0° to 95°	
<u> </u>	(0° is spring return position)	
Manual override	5 mm hex crank (3/16" Allen), supplied	
Humidity	max. 95% RH, non-condensing	
Ambient temperature	-22 to 122° F (-30 to 50° C)	
Storage temperature	-40 to 176° F (-40 to 80° C)	
Housing	NEMA 2, IP54, Enclosure Type 2	
Housing material	zinc coated metal and plastic casing	
Noise level	\leq 40dB(A) motor @ 150 seconds, run time dependent	
	≤62dB(A) spring return	
Agency listings +	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-	
	1:02, CE acc. to 2004/108/EC & 2006/95/EC	
Quality standard	ISO 9001	
Servicing	maintenance free	
Weight	4.3 lbs. (1.92 kg)	

† Rated Impulse Voltage 800V, Type of action 1.AA (1.AA.B for -S version), Control Pollution Degree 3.

LonWorks®	
Certified	according to LonMARK® 3.3
Processor	Neuron 3120
Transceiver	FTT-10A, compatible with LPT-10
Functional profile	according to LonMARK [®] Damper
	actuator object #8110
	open loop sensor object #1
LNS plug-in for actuator/sensor	can be run with any LNS based integration
	tool (min. for LNS 3.x)
Service button and status LED	according to LonMARK [®] guidelines
Conductors, cables	conductor lengths, cable specifications and
	topology of the LonWorks [®] network according to
	the Echelon® directives
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• Torque min. 180 in-lb

Feedback 2 to 10 VDC

Application

Direct coupled actuators for direct link to LonWorks network. Actuators are easily installed by direct shaft mounting on air dampers in ventilation and air conditioning systems. Actuator can be controlled by any compatible LON system. For proportional modulation of dampers and control valves in HVAC systems. The AFX24LON provides mechanical spring return operation for reliable fail-safe application.

Operation

The AFX24LON actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position.

The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches.

The AFX24LON is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The AFX24LON actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.



BELIMO

LonWorks [®] ,	Pro	portional	Spring	Return	, 24 \

AFX24LON

Accessories		
AV 8-25	Shaft extension	
IND-AFB	Damper position indicator	
KH-AFB	Crank arm	
K7-2	Universal clamp for up to 1.05" dia jackshafts	
TF-CC US	Conduit fitting	
Tool-06	8mm and 10 mm wrench	
ZG-100	Universal mounting bracket	
ZG-101	Universal mounting bracket	
ZG-102	Multiple actuator mounting bracket	
ZG-118	ZG-118 Mounting bracket for Barber Colman® MA 3/4, Honeywell®	
	Mod III or IV or Johnson® Series 100 replacement or new crank	
	arm type installations	
ZG-AFB	Crank arm adaptor kit	
ZG-AFB118	Crank arm adaptor kit	
ZS-100	Weather shield (metal)	
ZS-150	Weather shield (polycarbonate)	
ZS-260	Explosion-proof housing	
ZS-300	NEMA 4X housing	
NOTE: When using AFX24LON actuator only use accessories listed on this page		

NOTE: WHEN USING AFA24LON actuator, only use accessories listed on this

Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide proportional damper control in response to a LonWorks controller. The actuators must be designed so that they may be used for either clockwise or counterclockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators shall be cULus Approved and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.





Sensor scaling:

The sensors can be scaled with the sensor plug-in (sensor table).

Sensor	Temperature range	Resistance range	Resolution
Ni1000	−28 +98°C	850 1600 Ω	1Ω
PT1000	−35 +155°C	850 1600 Ω	1 Ω
NTC	-10 +160°C (depending on type)	200 60 k Ω	1 Ω

Connection with Passive Sensor, e.g. Pt1000, Ni1000, NTC



Connection with Switching Contact, e.g. Δp -monitor



LonWorks®, Proportional, Spring Return, 24 V



Functional Profile according to LonMARK®

The LON-capable damper actuator is certified by LonMARK[®]. The actuator functions are supplied with the LonWorks[®] network as standardized network variables according to LonMARK[®]. The Node Object #0, the Damper Actuator Object #8110 and the Open Loop SensorObject #1 are implemented in the actuator.



Node object #0

The node object contains the object status and object request functions.

nviRequest SNVT_obj_request Input variable for requesting the status of a particular object in the node.

nvoStatus SNVT_obj_status Output variable that outputs the current status of a particular object in the node.

nvoFileDirectory SNVT address

Output variable that shows information in the address range of the Neuron chip.

Damper actuator object #8110

The actuator object is used to map the functions of the MP actuators to the LONWORKS® network.

nviRelStpt SNVT_lev_percent

The nominal position is assigned to the actuator via this input variable. This variable is normally linked to the output variable of an HVAC controller.

nviActuateState SNVT_switch

A preset position is assigned to the actuator via this input variable. Note on priority: The last variable that was active, either nviActuatorState or nviRelStpt, has priority.

nviManOvrd SNVT_hvac_overid

These input variables can be used to manually override the actuator into a particular position.

nvoActualValue SNVT_lev_percent

This output variable shows the current actual position of the actuator and can be used for control circuit feedback or for displaying positions.

nvoAbsAngle SNVT_angle_deg

This output variable shows the current angle of rotation of the actuator

or the valve and can be used to display the position or for service purposes.

nvoAbsAirFlow SNVT_flow

This output variable is inactive with the SR24ALON-5 rotary actuator and shows a constant value of 65535 (this variable is only active in conjunction with LON-capable VAV controllers).

Open loop sensor object #1

A sensor can be connected to the rotary actuator. A passive resistance sensor (e.g. Ni1000), an active sensor (output 0 ... 32 V) or a switch (on/off) can be connected. The open loop sensor object transfers the measured sensor values to the LONWORKS® network.

nvoSensorValue SNVT_xxx

This output variable shows the current sensor value. Depending on the connected sensor, the output variable can be configured via the sensor plug-in and specifically adapted to the system.

The SNVT can be configured as:			
SNVT_temp_p	SNVT_lev_percent	SNVT_lux	
SNVT_temp	SNVT_abs_humid	SNVT_press_p	
SNVT_switch	SNVT_enthalpy	SNVT_smo_obscur	
SNVT_flow	SNVT_ppm	SNVT_power	
SNVT_flow_p	SNVT_rpm	SNVT_elec_kwh	

Notes

Detailed information on the functional profiles can be found on the website of LonMARK $^{\otimes}$ (www.lonmark.org).





1	Membrane key and green LED display		
	Off	No voltage supply or malfunction	
	On	Operation	
	Press button	Switches on angle of rotation adaption followed	
		by standard operation	
2	2 Membrane key and yellow LED display		
	Off	The actuator is integrated ready-for-operation in	
		the LONWORKS® network.	
	On	No application software is loaded in the actuator	
	Blinking	The actuator is ready-for-operation, but not	
	(flashing interval 2 seconds)	integrated in the LONWORKS® network	
		(unconfigured).	
	Other flashing codes	A fault is present in the actuator.	
	Press button	Service Pin Message will be sent to the	
		LONWORKS® network.	
3	Service plug		

For connecting MFT parameterizing and service tools

Operating Controls

The hand crank, interlocking switch and direction of rotation switch are provided on both sides.