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$20+$ years direct coupled actuator design.

| SEE PAGE NUMBER |  | 425 | 374 | - | 373 | 418 | 419 | 420 | 421 | 423 | 423 | 423 | 422 | 425 | 426 | Refer to MFT Technical Documentation |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BELIMO ACTUATOR |  | $\frac{8}{\dot{j}}$ |  | $\stackrel{\rightharpoonup}{0}$ |  |  | 눈 <br> 츨 | $\begin{aligned} & \text { 을 } \\ & \stackrel{i}{1} \\ & \underline{\underline{x}} \end{aligned}$ | $\begin{aligned} & \text { 운 } \\ & \dot{\omega} \end{aligned}$ | 둔 N |  |  |  | $\begin{aligned} & \text { 炰 } \\ & \text { N } \end{aligned}$ | 돛 |  |  |  | $\begin{aligned} & \text { Z } \\ & \stackrel{1}{4} \\ & \frac{1}{N} \end{aligned}$ | 른 $\stackrel{y}{N}$ | 랜 N゙N |
| AF24 (-S) US |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |
| AF120 (-S) US |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |
| AF230 (-S) US |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |
| AF24-SR US |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ | $\bullet$ |  | - | $\bullet$ | $\bullet$ |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |
| AFB24-MFT (-S), AFX24-MFT (-S) |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  | $\bullet$ |  |
| AFB24-MFT95, AFX24-MFT95 |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  | $\bullet$ |  |
| AF24-PC US |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |
| NFB24 (-S), NFX24 (-S) |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |
| NFBUP (-S), NFXUP (-S) |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| NFB24-SR (-S), NFX24-SR (-S) |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | - | $\bullet$ |  |  | $\bullet$ |  |  |  |  |  |  |  |
| NFB24-MFT (-S), NFX24-MFT (-S) |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  | $\bullet$ |  |
| LF24 (-S) US |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |
| LF120 (-S) US |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| LF230 (-S) US |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| LF(C)24-3...US |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |
| LF24-SR...US |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  | $\bullet$ |  |  |  |  |  |  |  |
| LF24-ECON...US |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |
| LF24-MFT...US |  | $\bullet$ |  | $\bullet$ |  | $\bullet$ |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  |  |  |
| TF24 (-S) US |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |
| TF120 (-S) US |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| TF24-3 (-S) US |  | $\bullet$ |  |  |  |  |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |
| TF24-SR (-S) US |  | $\bullet$ |  |  |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |  |  | $\bullet$ |  |  |  |  |  |  |  |
| GM_24-3 |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| GMX120-3 |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |
| GM_24-SR |  | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ | - | - | - | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| GMX24-MFT |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| GMX24-MFT95 |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  | - | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| GMX24-PC |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| AM_24-3(-S)(-T) |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| AM120-3 |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |
| AM_24-SR(-T) |  | - | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | - | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| AMX120-SR |  |  | $\bullet$ | $\bullet$ | - | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |
| AMX24-MFT |  | - | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  | - | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | - | - | $\bullet$ |
| AMX24-MFT95 |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| AMX24-PC |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| NM_24-3(-T) |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| NM120-3 |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |
| NM_24-SR(-T) |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| NM120-SR |  |  | $\bullet$ | $\bullet$ | - | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |
| NMX24-MFT |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | - | $\bullet$ | - | $\bullet$ |
| NMX24-MFT95 |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| NMX24-PC |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| NMQ24-MFT US |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| LM_24-3 (-P5) (-P10) (-S) (-T) |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| LMX120-3 |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  | $\bullet$ |  |  |  |  |  |  |  |  |
| LM_24-SR(-T) |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |
| LMX120-SR |  |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ |  | $\bullet$ |  |  |  |  |  |  |  |  |
| LMX24-MFT |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| LMX24-MFT95 |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |  |  |  |  | $\bullet$ | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| LMX24-PC |  | $\bullet$ | $\bullet$ | $\bullet$ | - |  |  |  |  |  |  |  | $\bullet$ | $\bullet$ |  |  |  |  |  |  |  |



| Technical Data | SGA24, SGF24 |
| :--- | :--- |
| Power supply | 24 VAC $\pm 20 \% 50 / 60 \mathrm{~Hz}, 24 \mathrm{VDC} \pm 10 \%$ |
| Transformer sizing | 1 VA |
| Control signal Y | 0.5 to 10 VDC; 2 to 10 VDC (switchable) |
| Power output | up to 10 actuators (1 mA max) |
| Degree of protection | (SGA24 only NEMA 2 [IP54]) |
| Connection | Terminals (14 ga. wire max) |
| Humidity | 5 to $95 \%$ RH non-condensing |

## Wiring Diagrams



Minimum Position Setting

$\triangle$
Provide overload protection and disconnect as required.
Override switches are optional.
3. A $500 \Omega$ resistor (ZG-R01) must be added for 4 to 20 mA control.

## Application

These positioners are intended for the remote control of modulating actuators or for use as a minimum positioner (providing a minimum limit for the output signal from a modulating controller). The control range is 0 to $100 \%$ of the angle of rotation of the actuator.

Positioner SGA24 is for surface mounting with a NEMA 2 housing included. Positioner SGF24 is for flush mounting.

## Operation

The positioner receives its supply voltage through terminals 1 and 2 . A rotary knob is turned, producing a proportional control signal $(\mathrm{Y})$ at the output (terminal 3 ) of either 0.5 to 10 VDC or 2 to 10 VDC and therefore a proportional change in the position of the actuator between 0 and 100\%. When used for a minimum limit, the positioner works as a higher of 2 signal selector. This function allows only the signal from the controller or positioner, whichever is greater, to go to the actuator.

## Function

The changeover from 2 to 10 V to 0 to 10 V is selected by means of a slide switch on the printed circuit board.

The angle of rotation of the knob can be limited mechanically, by moving the adjustable stops under the knob.

## Accessory



Drilling template for SGF24 (flush mount)



| Technical Data | PTA-250 |
| :---: | :---: |
| Power supply | 24 VAC $\pm 15 \% 24$ VDC $\pm 15 \%$ |
| Power consumption | <1 W |
| Transformer sizing | 2 VA |
| Input |  |
| Isolation | optically isolated (when wired as such) |
| Type | normal or triac, jumper selectable |
| Trigger level | 12 to 24 VAC/VDC or dry contact to com |
| Time between trigger pulses | 12.5 milliseconds min |
| Impedance | VAC - $500 \Omega$, VDC - $10 \mathrm{k} \Omega$ |
| Pulse duration/resolution | four selectable ranges, in seconds of dry contact or SSR closure $\pm 40 \%$ of signal increment |
| Range 1 | 0.0235 to 6 seconds/in 0.0235 sec increments |
| Range 2 | 0.0196 to 5 seconds/in 0.0196 sec increments |
| Range 3 | 0.1 to 25.5 seconds/in 0.100 sec increments |
| Range 4 | 0.59 to 2.93 seconds/in in 0.0092 increments |
| Output |  |
| Voltage | 2 to 10 VDC |
| Current | 15 mA max |
| Accuracy | $\pm 2 \%$ |
| Electrical connection | wire terminals, 14 gauge max |
| Ambient temperature | $-20^{\circ} \mathrm{F}$ to $150^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.65^{\circ} \mathrm{C}\right]$ |
| Operating humidity | 5\% to 95\% non-condensing |
| Mounting | Snap-Track (provided) |
| Dimensions board | $23 / 16^{\prime \prime} \times 23 / 16^{\prime \prime} \times 9 / 16^{\prime \prime}$ |
| with Snap-Track | $23 / 8^{\prime \prime} \times 2$ 1/4" $\times 15 / 16^{\prime \prime}$ |
| Weight | 1.50 z |

## Wiring Diagram



[^0]Provide overload protection and disconnect as required.
2. Actuator and controller must have separate transformers.
3. Consult controller instruction data for more detailed installation information

4 To reverse control rotation, use the reversing switch.
5. The PTA-250 and actuator may be powered from the same transformer

## Application

The PTA-250 converts a single pulse-width modulated input to an analog, 2 to 10 VDC, output to modulate a Belimo -SR actuator. The PTA-250 is available for replacement of existing installations. The ...MFT product can replace 100\% of the PTA-250 applications, more effectively.

## Operation

A timed contact or solid state closure from the controlling microprocessor controller is converted to a linear analog output with 256 steps of resolution. The last output is held until the PTA-250 receives the end of the next pulsed output. The PTA-250's output will not wrap around if an excessively long input pulse is received. Four input pulse clock rates are jumper selectable. Normal/Triac input positions are also jumper selectable. The input signal can be optically isolated from the PTA-250 circuit and can accept either positive or negative polarity. A red LED indicator is provided to indicate that power is applied to the PTA-250 and that the microprocessor is functioning. A green LED indicator is provided to indicate the presence of a pulse from the controller.
NOTE: The onboard zero and span adjustments are not for field use.



| Technical Data | IRM-100 |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \mathrm{VAC} \pm 15 \% \\ & 24 \mathrm{VDC} \pm 15 \% \end{aligned}$ |
| Power consumption | $<1 \mathrm{~W}$ |
| Transformer sizing | 1 VA |
| Input |  |
| Voltage (max) | 25 VDC |
| Zero (starting point) | 0 to 18 VDC |
| Span adjustment | 2.6 to 17 VDC |
| Impedance | $400 \mathrm{k} \Omega$ |
| Current | 0 to 20 mA |
| Impedance | $500 \Omega$ |
| Output |  |
| Voltage | 2 to 10 VDC |
| Current | 15 mA max |
| Electrical connection | wire terminals, 14 gauge max |
| Ambient temperature | $-20^{\circ} \mathrm{F}$ to $150^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.65^{\circ} \mathrm{C}\right]$ |
| Humidity | 5 to 95\% RH non-condensing |
| Mounting | Snap-Track (provided) |
| Dimensions board | 1-3/16" x 2-3/16" x 9/16" |
| with Snap-Track | 1-7/8" $\times 2-3 / 8^{\prime \prime} \times 15 / 16^{\prime \prime}$ |
| Weight | 0.9 oz . |

## Wiring Diagram



1 Provide overload protection and disconnect as required.
22 The controller should be powered from a separate transformer.
3 The actuator and IRM-100 may be powered from the same transformer.
4 Consult controller instruction data for more detailed installation information.
5. To reverse control rotation, use the reversing switch.

## Application

The IRM-100 input rescaling module is designed to change non-standard voltage or current signal levels into a 2 to 10 VDC output to modulate Belimo -SR type actuators. The IRM-100 is available for replacement of existing installations. The ...MFT product can replace $100 \%$ of the IRM-100 applications, more effectively.

## Operation

The IRM-100 is installed between a controller and a Belimo ...-SR actuator. The module can be adjusted to work with a zero offset of 0 to 18 VDC and a span range of 2.6 to 17 VDC. The IRM-100 has a 2 pin jumper mounted to the circuit board. When the jumper is connected between these 2 pins, a 4 to 20 mA signal can be fed directly into the IRM. The result being the conversion of a wide range of analog control signals to a 2 to 10 VDC range.


Jumper on both pins for 4 to 20 mA applications

The IRM may also be used to sequence several actuators from one signal source. This is done by adjusting the IRM units to work at different in put ranges.

## IRM-100 Used as a Current Amplifier

In some applications, the capacity of a controller output may not have current available to control multiple end devices. An example would be a controller which has an output current of .5 mA maximum. If 10 AF24-SR US actuators have to be driven from the same output, the current requirement would be $\mathrm{I}=\mathrm{E} / \mathrm{R}=(10 \mathrm{volts}) /(100000$ $\Omega)=.1 \mathrm{~mA}$ for each actuator. For the 10 actuators, 1 mA of current would be necessary to properly control the actuators.
The IRM-100 may be used as an interface to provide a higher current capacity to the system. The IRM-100 has an output capacity of 15 mA . This higher level output can handle a greater number of actuators. By calibrating the IRM-100 for a 2 to 10 VDC input to achieve a 2 to 10 VDC output, IRM-100 provides this added capacity for the system.

The same circuit will also work if a 4 to 20 mA signal is used. A $500 \Omega$ resistor is placed across terminal \#1 and \#3 which converts the 4 to 20 mA to 2 to 10 VDC.

## Dimensions (Inches [mm])



## Analog to Digital Switch ADS-100

For Belimo Proportional ( ... -SR) Actuators


| Technical Data | ADS-100 |
| :--- | :--- |
| Power supply | $24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{HZ}$ |
| Power consumption | 1.5 W |
| Transformer sizing | 3 VA (not including contactors) |
| Electrical connection | 9 pole wire-terminal |
| Control input | 2 to 10 VDC |
| Input impedance | $100 \mathrm{k} \Omega$ |
| Adjusting range | 2.5 to 9.5 VDC |
| Dead band | $0.3^{\circ} \mathrm{F}$ fixed |
| Switching capacity | 24 VAC 10 VA max., (voltage sinking triac) |
| Mounting | Snap-Track (provided) |
| Dimensions $\quad$with |  |
|  | $3-1 / 4^{\prime \prime} \times 2^{\prime \prime}$ |



## Application

To control reheat coils and/or a fan stage in a fan-powered terminal unit. The ADS-100 is controlled by a 2 to 10 VDC reheat output of a temperature controller. (TRS-M)

## Operation

The ADS-100 is designed to switch up to three independent stages of reheat on and off, according to a 2 to 10 VDC signal. The three output stages are furnished with a triac output. Each stage can be adjusted independently from each other over the 0 to $2.4^{\circ} \mathrm{F}$ throttling range of the TRS-M temperature controller.

The ADS-100 is shipped pre-adjusted, as shown in the following table. (Based on differential from setpoint)

|  | 1st. stage | 2nd. stage | 3rd. stage |
| :--- | :---: | :---: | :---: |
| Switch ON | $-0.45^{\circ} \mathrm{F}$ | $-1.35^{\circ} \mathrm{F}$ | $-2.25^{\circ} \mathrm{F}$ |
| Switch OFF | $-0.15^{\circ} \mathrm{F}$ | $-1.05^{\circ} \mathrm{F}$ | $-1.95^{\circ} \mathrm{F}$ |
| Switch ON | 2.8 V | 5.8 V | 8.8 V |
| Switch OFF | 0.4 V | 0.2 V | 0.4 V |

If desired, each stage may be field readjusted for special requirements. Three red LED indicators are provided to verify when the stages are energized.

## Setpoint Readjustment

Tools required: small screwdriver, voltmeter.
To readjust the output stages, the following procedure is used:
Connect the voltmeter to the desired switchpoint reference signal output and terminal 1 (COM). Readjust the switch point reference signal output with the corresponding potentiometer to your desired switch point. The adjustment range is 2.5 to 9.5 VDC . If you go below or above these values the ADS-100 may not switch off or on properly. If this occurs you have to increase or decrease your switching level until the ADS-100 works correctly.

## ADS-100 Used as an Auxiliary Switch

The ADS-100 was originally designed as an accessory to switch on stages of electric reheat from an electronic thermostat. However, it can also function as an electronic auxiliary switch from any device which can provide 0 to 10 VDC signal, such as any feedback wire 5 from any ...SR or ...MFT type actuator.
The ADS-100 has 3 triac outputs rated at 10 VA maximum each which will turn on, in sequ ence, with an increasing voltage.

## Dimensions (Inches [mm])




| Technical Data |  |
| :--- | :--- |
| Power supply | $24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz}$ |
| Fusing | 4 A slow blow fuse |
| Power consumption | min. 5 W (without actuator load) |
| Transformer | 8 VA |
| Batteries | 24 V Nominal 1.2 Ah (2-12 volt lead-acid batteries; bat- <br> teries not supplied with module) |
| Maintenance | the batteries should be checked annually <br> (approximate life is 6 years) |
| Charging circuit | charge current max. 150 mA <br> charge voltage 24-27 V, temperature compensated |
| Battery back-up | 24 V nominal 1.2 Ah, max. 60 W <br> auto shut off after 250 seconds |
| operation | green - main power source operation <br> (battery will be charged) <br> red - battery back-up operation |
| Mounting | mounted in the control panel with an 11 terminal plug-in <br> base (not supplied with module) |
| Ambient temperature | $14^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-10^{\circ} \mathrm{C} \ldots 50^{\circ} \mathrm{C}\right]$ |

## Dimensions (Inches [mm])



## Application

Several Belimo damper actuators can be used either with 24 VAC or 24 VDC.
In case of a power failure, the NSV24 battery back-up unit switches the damper actuator from its main AC power supply over to the 24 VDC battery to drive the actuators to their safety position.

For easy maintenance, the battery back-up system is placed in the control panel, not in the actuator. Several actuators may be powered by one back-up module. The batteries are separate from the NSV24.

## Operation

The NSV24 is connected to the same 24 VAC power source as the damper actuators. It also charges the 24 V (2-12 volt batteries) storage battery. Its charge current is limited to 150 mA maximum, and the maximum charge voltage is temperature compensated.

In case of a power failure, the NSV24 switches immediately over to the battery power source, and according to the control function, the actuators will move to their safety position. After 250 seconds, the batteries are disconnected from the actuators to prolong battery life. Because of this, a safe battery back-up can be provided for several short-term failures. The main power source operation is indicated by a green LED, and the battery power source by a red LED.

| Connectable Actuator Models |  |
| :--- | :--- |
| GMB24-3X1 | Maximum per module |
| GMX24-3 | 15 |
| GMX24-MFTX1 | 15 |
| GMB24-SR | 15 |
| AMB24-3 | 30 |
| AMX24-MFT | 30 |
| AMB24-SR | 30 |
| NMB24-3 | 30 |
| NMX24-MFT | 30 |
| NMB24-SR | 30 |
| LMB24-3 | 30 |
| LMX24-MFT | 30 |
| LMB24-SR | 30 |

## Accessories

NSV-BAT $\quad 12$ VDC 1.2 Ah battery (2 required)

## Wiring Diagrams




This diagram is shown in the "failed" mode and prior to the 250 sec time-out function.


| Technical Data | NSV-BAT |
| :--- | :--- |
| Battery type | lead-acid |
| Voltage | 12 VDC |
| Nominal capacity | 1.2 AH |
| Connections | .187 male spade |
| Weight | $1.32 \mathrm{lb}[.6 \mathrm{~kg}]$ |

ZG-R01 Resistor for 4 to 20 mA conversions


## Application

The NSV-BAT battery is for use with the NSV24 battery back-up module. It is a sealed, maintenance free, lead-acid battery. Two NSV-BAT batteries are required for one NSV24.

Dimensions (Inches [mm])



## Application

The ZG-R01 is a $499 \Omega$ Resistor which has been encased in a section of heat shrink tubing with short sections of hook up wire.The ZG-R01 is used to convert a 4 to 20 mA signal into a 2 to 10 VDC control signal.
Dimensions (Inches [mm])


ZG-R02 50\% Voltage Divider


The impedance of the device attached must be $100 \mathrm{k} \Omega$.

## Application

The ZG-RO2 is a voltage divider designed so that when connected to a $100 \mathrm{~K} \Omega$ input impedance, the output signal is $50 \%$ if the input signal. The voltage divider circuit is encased in a short section of heat shrink tubing with three short sections of hook up wire.
Dimensions (Inches [mm])


## Resistor kits for Multiple Actuator Applications

| Resistor Kit No. ZG-R03 |  |
| :--- | :--- |
| $135 \Omega$ Operation |  |
| No. of Actuators | Resistance $\Omega$ |
| 2 | 140 |
| 3 | 71.5 |
| 4 | 47.5 |
| 5 | 37.5 |
| 6 | 28 |

Resistor Kit No. ZG-R05
4 to 20 mA Operation

| No. of Actuators | Resistance $\Omega$ |
| :--- | :--- |
| 1 | 237 |
| 2 | 150 |
| 3 | 124 |
| 4 | 113 |
| 5 | 105 |
| 6 | 97.6 |

Resistor Kit No. ZG-R06
For Honeywell『 Electronic Series 90 Circuits (W7100, W973, T775)
No. of Actuators Resistance $\Omega$

| 2 | 1300 |
| :--- | :--- |
| 3 | 910 |
| 4 | 768 |

## Application

For use with the ...MFT95 actuators and Honeywello controllers

| ZG-R03 | See table to left |
| :--- | :--- |
| ZG-R05 | See table to left |
| ZG-R06 | See table to left |



## ZG-CBLS Junction box



| Technical Data | ZG-CBNS / ZG-CBLS |
| :--- | :--- |
| Voltage rating | 250 VAC |
| Electrical connection | maximum 5 line voltage connection |
| Housing rating | UL94 5VA |
| Material type | FR/ABS CYCOLAC FR15 |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.80^{\circ} \mathrm{C}\right]$ |
| Agency listing | UL pending |
| Quality standards | ISO 9001 |
| Weight | $<0.5 \mathrm{lbs}$ |

## ZG-CBNS

## Application

The ZG-CBNS accessory is used when the application requires the wiring terminations to be made at the actuator.

## Operation

The ZG-CBNS serves as an electrical junction box. The products that can be used with this accessory are as follows:
AF24 US, AF120 US, AF230 US, AF24-SR US

* Due to the internal volume of this junction box, according to UL requirements, The ZG-CBNS CANNOT be used with the following products:

NF24-S2 US, AF24-S US, AF120-S US, AF230-S US

## ZG-CBLS

## Application

The ZG-CBLS accessory is used when the application requires the wiring terminations to be made at the actuator.

## Operation

The ZG-CBLS serves as an electrical junction box.
This product can be used with any standard LF product.

## Transformer ZGX40



## Application

The ZG-X40 is a 40 VA, 120 to 24 VAC transformer. It is designed so that both the primary and secondary leads exit through the same side of a 4-1/4" square outlet box cover. With this design, all wiring can be done inside a standard J-box with a minimum amount of labor.

| Technical Data | ZG-X40 |
| :--- | :--- |
| Primary voltage | 120 VAC $50 / 60 \mathrm{~Hz}$ |
| Secondary voltage | 24 VAC |
| Max VA rating | 40 VA |
| Connections | $6-1 / 2^{\prime \prime}$ leads with stripped ends |
| Type | Class 2 |
| Mounting method | $4-1 / 4$ " square outlet box cover |
| Agency approvals | UL 1585, CSA 22.2 \#66 |
|  |  |
| Wire Specification | No. 18 AWG leads, 6-1/2" length |
| Wire | Color |
| Termination | White-Black |
| Primary | Yellow-Yellow |
| Secondary |  |



| Original AF24..US | 4 |
| :--- | :--- |

Refer to appropriate actuator documentation for specific VA ratings.


## Wiring Diagram



Power Supply, Signal Simulator PS-100


## Application

The PS-100 power supply and signal simulator is designed to operate most proportional, floating, and On/Off style actuators without the presence of a controller.

The PS-100 can produce 24 VAC $0 n / 0 f f$ and floating control signal along with a 0 to 10 VDC and $135 \Omega$ proportional signal. A multi-function digital display is provided which can read either the 0 to 10 VDC output or a 0 to 10 VDC feedback signal either as voltage or percentage of control.

The PS-100 comes with a 120 to 24 VAC, plug into the wall transformer for power. Both the PS-100 and transformer are supplied in a black fabric carrying case.
Replacement Power Supply: PS-XFMR

| Technical Data | PS-100 |
| :---: | :---: |
| Power supply | 120 VAC 50/60 Hz |
| Power consumption | $<4 \mathrm{~W}$ without actuator |
| Transformer Primary | 120 VAC, 35 W |
| Secondary | 24 VAC, Class 2 trans. |
| PN | PS-XFMR |
| Terminal outputs | push-button, wire terminals (12) <br> on/off, floating point, $135 \Omega$, 0 to 10 VDC |
| VDC output range | 0 to 10 VDC |
| Display | LCD |
| Readouts Output | 0 to 10 VDC in volts or percentage based on a 2 to 10 VDC control span |
| Input | 0 to 10 VDC in volts or percentage based on a 2 to 10 VDC control span |
| Weight | 3 lbs [1.4 kg] with case |

Dimensions (Inches [mm])



| Technical Data | ZG-HTR |
| :--- | :--- |
| Power supply | $24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz}$ |
| Transformer sizing | 35 VA |
| Heater output | 35 watts |
| Actuator low ambient rating <br> with enclosure <br> enclosure with 1" insulation | $-40^{\circ} \mathrm{F}\left[-58^{\circ} \mathrm{C}\left[-50^{\circ} \mathrm{C}\right]\right.$ |
| Weight | $110 \mathrm{oz}[320 \mathrm{~g}]$ |

## Application

The ZG-HTR Thermostat/Heater kit is designed to be field installed to the original AF and NF series actuators. The ZG-HTR provides a thermostatically controlled heater which allows the original AF and NF actuators to be used below their normal low ambient temperature rating. At approximately $10^{\circ} \mathrm{F}\left[-12^{\circ} \mathrm{C}\right]$ the heater energizes to maintain the actuators internal temperature to within working limits. The rubberized heating element has an adhesive back which attaches to the side of the actuator housing. The thermostat assembly mounts to the rear of the actuator and provides for the connection of the 24 VAC supply voltage. The actuator/heater assembly should be contained in a housing, similar to the ZS-100 Weather Shield, to achieve best results.

## Wiring Diagram



1Provide overload protection and disconnect as required.
The ZG-HTR may be wired to the same transformer as the actuator. Total VA ratings must be observed.
Power to the ZG-HTR must be applied continuously during the heating season. Do not wire the ZG-HTR to the on-off control signal when on-off type actuators are being used.

## Dimensions (Inches [mm])

## Standard:

Ø $3 / 8^{\prime \prime}$ to $3 / 4^{\prime \prime}$
$3 / 8^{\prime \prime}$ to $5 / 8^{\prime \prime}$
Optional*
Ø $3 / 4^{\prime \prime}$ to 1.05 "
*with K4-1 US clamp


| Special Control Range Applications |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Control Signal | Belimo Actuat |  | Accessory | Notes |
| 1 to 5 VDC | AFX24-MFT <br> NFX24-MFT <br> LF24-MFT US <br> TF24-MFT US | GMX24-MFT <br> AMX24-MFT <br> NMX24-MFT <br> LMX24-MFT | None | Preset at factory or use PC tool software. <br> Set start point for 1 VDC, span for 4 VDC. |
| 4 to 20 mA | Any -MFT,-SR Actuator |  | $\begin{array}{\|l\|} \hline \text { ZG-R01, or } \\ 500 \Omega, 1 / 2 \mathrm{~W} \text { resistor } \end{array}$ | Wire the ZG-R01 across the wires \#1 and \#3. |
| 10.5 to 13.5 VDC | AFX24-MFT <br> NFX24-MFT <br> LF24-MFT US <br> TF24-MFT US | GMX24-MFT <br> AMX24-MFT <br> NMX24-MFT <br> LMX24-MFT | None | Preset at factory or use PC tool software. <br> Set start point for 10.5 VDC , span for 3 VDC. |
| 14 to 17 VDC | AFX24-MFT <br> NFX24-MFT <br> LF24-MFT US <br> TF24-MFT US | GMX24-MFT <br> AMX24-MFT <br> NMX24-MFT <br> LMX24-MFT | None | Preset at factory or use PC tool software. <br> Set start point for 14 VDC, span for 3 VDC. |
| Pulse Width Modulation | AFX24-MFT <br> NFX24-MFT <br> LF24-MFT US <br> TF24-MFT US | GMX24-MFT <br> AMX24-MFT <br> NMX24-MFT <br> LMX24-MFT | None | Preset at factory or use PC tool software. |

*Preset at factory or use MFT PC tool software
IRM-100 Calibrate the IRM-100 for an input range of 1 to 5 VDC. Calibrate IRM-100 2-10 in 2 to 10 out for signal amplification.

Sequencing Two or More Actuators With One Control Signal using the IRM-100



[^0]:    1
    2
    2
    3
    4
    4
    4

