









Technical Data	GKB24-SR-T N4		
Power supply	24 VAC ± 20% 50/60 Hz		
	24 VDC ± 10%		
Power consumption	12 W (3 W)		
Transformer sizing	21 VA (Class 2 power source)		
Electrical connection	screw terminal (for 26 to 14 GA wire)		
	½" conduit connector		
Overload protection	electronic throughout 0 to 95° rotation		
Operating range Y	2 to 10 VDC, 4 to 20 mA		
Input impedance	100 kΩ		
Feedback output U	2 to 10 VDC (max 0.5 mA)		
Angle of rotation	max. 95°, adjustable with mechanical stop		
Torque	360 in-lb [40 Nm]		
Direction of rotation	reversible with \bigcirc/\bigcirc switch		
Position indication	dial		
Running time	150 seconds, constant independent of load		
Motor fail-safe	35 seconds		
Humidity	5 to 100% RH (UL Type 4)		
Ambient temperature	-22°F to 122°F [-30°C to 50°C]		
Storage temperature	-40°F to 176°F [-40°C to 80°C]		
Housing	UL Type 4, NEMA 4, IP66		
Housing material	polycarbonate		
Agency listings†	cULus acc. to UL 60730-1A/-2-14,		
	CAN/CSA E60730-1, CSA C22.2 No. 24-93,		
	CE acc. to 89/336/EEC		
Noise level	<45dB(A)		
Servicing	maintenance free		
Quality standard	ISO 9001		
Weight	10.4 lbs [4.71 kg]		

[†]Rated Impulse Voltage 800V, Type of action 1, Control Pollution Degree 3.

Torque min. 360 in-lb for control of damper surfaces up to 90 sq ft.

Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to 1.05" in diameter by a universal clamp.

The actuator operates in response to a 2 to 10 VDC, or with the addition of a 500 Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

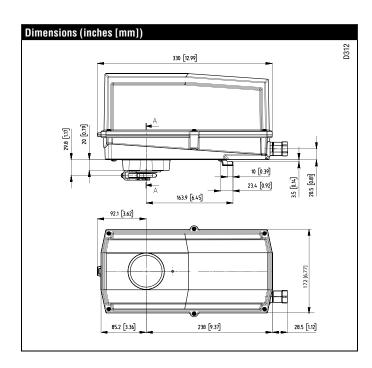
Operation

The actuator is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The GKB24-SR-T N4 provides 95° of rotation and a visual indicator shows the position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged by pressing the button located on the actuator cover.

The GKB24-SR-T N4 actuator uses a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.





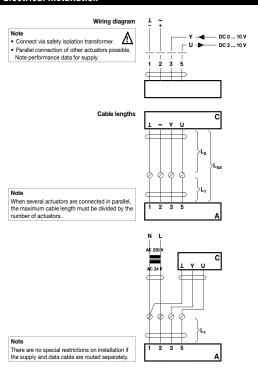
Accessories			
S1A, S2A	Auxiliary Switch(es)		
PA	Feedback Potentiometers		
SGA24	Min positioners for surface mounting		
SGF24	Min positioners for flush panel mounting		
PTA-250	Pulse Width Modulation Interface		
IRM-100	Input Rescaling Module		
ADS-100	Analog to Digital Switch		
ZG-R01	Resistor for 4 to 20 mA Conversion		
NSV24 US	Battery Back-Up Module		
ZG-X40	Transformer		
43442-00001	Gland (needed for additional wires)		
11097-00001	Gasket for Gland		

Note: When using GKB24-SR-T N4 actuators, only use accessories listed on this page.

Typical Specification

Proportional control damper actuators shall be electronic direct-coupled type. which require no crank arm and linkage and be capable of direct mounting to a shaft up to 3/4" diameter. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500 Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Electrical Installation



C	al	ole colors:
1	=	black
		red

= Actuator = Control unit = Belimo connecting cable, 1 m (4 x 0.75 mm²) = Customer cable

= Maximum cable length

Cross section L ₂	Max. cable length L _{tot} = L ₁ + L ₂		Example for DC
1/~	AC	DC	
0.75 mm ²	≤30 m	≤5 m	1 m (L ₁) + 4 m (L ₂)
1.00 mm ²	≤40 m	≤8 m	1 m (L ₁) + 7 m (L ₂)
1.50 mm ²	≤70 m	≤12 m	11 m (L ₁) + 11 m (L ₂)
0.503	400	00	4 (1) - 40 (1)

Control unit

Belimo connecting cable, 1 m (4 x 0.75 mm²)

Wiring Diagrams

INSTALLATION NOTES



Provide overload protection and disconnect as required.



CAUTION Equipment Damage!

Actuators may be connected in parallel.

Power consumption and input impedance must be observed.



Actuators may also be powered by 24 VDC.



Only connect common to neg. (-) leg of control circuits



APPLICATION NOTES



The ZG-R01 500 Ω resistor converts the 4 to 20 mA control signal to 2 to 10 VDC, up to 2 actuators may be connected in parallel.



WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

