


Force min. 27 in-lb for control of damper surfaces up to 6.8 sq . ft .

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator operates in response to a 2 to 10 VDC, or with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The LUB $(X)$ series provides $330^{\circ}$ of rotation with angle of rotation limiter, ZDB-LU.
When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The LUB(X)24-SR actuators use a brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. Power consumption is reduced in holding mode.

## Dimensions (Inches [mm])



| Accessories |  |
| :--- | :--- |
| K-LU | $1 / 3^{\prime \prime}$ to $1 / 2^{\prime \prime}[8$ to 12 mm$]$ Shaft Clamp |
| P370 | Shaft Mount Auxiliary Switch |
| SGA24 | Min Positioners in NEMA 4 Housing |
| SGF24 | Min Positioners for Flush Panel Mounting |
| PTA-250 | Pulse Width Modulation Interface |
| IRM-100 | Input Rescaling Module |
| ADS-100 | Analog to Digital Switch |
| ZG-R01 | Resistor for 4 to 20 mA Conversion |
| NSV24 US | Battery Back-Up Module |
| ZG-X40 | Transformer |
| ZDB-LU | Rotational Limiter |
| NOTE: |  |

NOTE: When using LUB(X)24-SR actuators, only use accessories listed on this page.

## Typical Specification

Proportional control damper actuators shall be electronic type, which require no crank arm and linkage. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushes DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cL Approved, have a 5 -year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

## X INSTALLATION NOTES

Provide overload protection and disconnect as required.

## CAUTION Equipment Damage!

Actuators may be connected in parallel.
Power consumption and input impedance must be observed.


Actuators may also be powered by 24 VDC .
Only connect common to neg. (-) leg of control circuits.

## - APPLICATION NOTES

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The ZG-R01 $500 \Omega$ resistor converts the 4 to 20 mA control signal to 2 to 10 VDC , up to 2 actuators may be connected in parallel.

## WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.


Proportional, 4 to 20 mA control

