## NMB24-SR-T N4, NMB24-SR-T N4H

NEMA 4X, Proportional Control, Non-Spring Return, Direct Coupled, 24V, for 2 to 10 VDC and 4 to 20 mA











Technical Data	NMB24-SR-T N4, NMB24-SR-T N4H
Power supply	24 VAC ± 20% 50/60 Hz
Towor Suppry	24 VDC ± 10%
Power consumption	3.5 W (0.6 W) / heater 24 W
Transformer sizing	5 VA (Class 2 power source) / heater 20 VA
Electrical connection	screw terminal (for 26 to 14 GA wire [heater 15 GA wire])
Overdeed much etter	1/2" conduit connector
Overload protection	electronic throughout 0 to 95° rotation
Operating range Y	2 to 10 VDC, 4 to 20 mA
Input impedance	100 kΩ (0.1 mA), 500 Ω
Angle of rotation	max. 95°, adjustable with mechanical stop
Torque	70 in-lb [8 Nm]
Direction of rotation	reversible with $\bigcirc/\bigcirc$ switch
Position indication	pointer
Manual override	external push button
Running time	55 seconds
	constant independent of load
Humidity	5 to 95% RH non condensing (EN 60730-1)
Ambient temperature	-22°F to 122°F [-30°C to 50°C]
Storage temperature	-40°F to 176°F [-40°C to 80°C]
Housing	UL type 4X, NEMA 4X, IP66/67
Housing material	UL94-5VA
Agency listings†	cULus acc. to UL 60730-1A/-2-14, CAN/CSA E60730-1, CSA C22.2 No. 24-93, CE acc. to 89/336/EEC
Noise level	<45dB(A)
Servicing	maintenance free
Quality standard	ISO 9001
Weight	2.8 lbs [1.2 kg] 3.2 lbs [1.4 kg]

 $<sup>\</sup>dagger$ Rated Impulse Voltage 800V, Type of action 1, Control Pollution Degree 3.

### Torque min. 70 in-lb for control of damper surfaces up to 16 sq ft.

### **Application**

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to 34" in diameter by means of its universal clamp.

The actuator operates in response to a 2 to 10 VDC, or with the addition of a 500  $\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

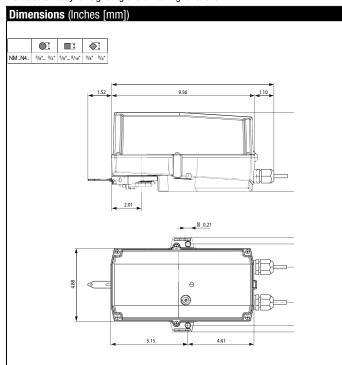
#### **Operation**

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The NMB24-SR-T N4 provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The NMB24-SR-T N4 actuator uses a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.





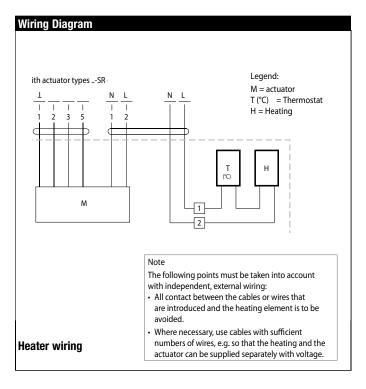


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Accessories	
S1A, S2A	Auxiliary Switch (es)
PA	Feedback Potentiometers
SGA24	Min positioners for surface mounting
SGF24	Min positioners for flush panel mounting
PTA-250	Pulse Width Modulation Interface
IRM-100	Input Rescaling Module
ADS-100	Analog to Digital Switch
ZG-R01	Resistor for 4 to 20 mA Conversion
NSV24 US	Battery Back-Up Module
ZG-X40	Transformer

### **Typical Specification**

Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft up to  $3\!4"$  diameter. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500  $\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, NEMA 4X, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



### **Wiring Diagram**

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### INSTALLATION NOTES



Provide overload protection and disconnect as required.



## **CAUTION** Equipment damage!

Actuators may be connected in parallel.

Power consumption and input impedance must be observed.



Actuators may also be powered by 24 VDC.



Only connect common to neg. (-) leg of control circuits.



## **APPLICATION NOTES**



The ZG-R01 500  $\Omega$  resistor converts the 4 to 20 mA control signal to 2 to 10 VDC, up to 2 actuators may be connected in parallel.

# WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

