## Minimum 101 lbf Linear Force

- For damper surfaces up to 32 sq-ft*


## AH Series - At A Glance

| AH | A Clance | $\frac{\sqrt{2}}{4}$ | 줒 | $\frac{0}{\top}$ | 줒 | 줒 |  | 웆 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Basic Product |  | - |  | - |  |  | $\bullet$ | $\bullet$ |
| Flexible Product |  | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ | $\bullet$ |
| Linear Force | $101 \mathrm{lbf}[450 \mathrm{~N}]$ | - | $\bullet$ | - | $\bullet$ | - |  |  |
|  | 44 lbf [200 N] |  |  |  |  |  | $\bullet$ | $\bullet$ |
| Linear Stroke | 4" | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
|  | 8" | $\bullet$ | $\bullet$ | - | $\bullet$ | - |  |  |
|  | 12" | $\bullet$ | $\bullet$ |  | $\bullet$ | $\bullet$ |  |  |
| Power Supply | 24 VAC/DC | $\bullet$ |  | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ |
|  | 120 VAC |  | $\bullet$ |  | $\bullet$ |  |  |  |
| Control Input | On/Off |  |  |  |  |  | $\bullet$ |  |
|  | On/Off, Floating Point | $\bullet$ | $\bullet$ |  |  |  |  |  |
|  | 2 to 10 VDC (4 to 20mA) |  |  | - | $\bullet$ |  |  |  |
|  | Multi-Function Technology |  |  |  |  | - |  | $\bullet$ |
| Feedback | None | $\bullet$ | $\bullet$ |  |  |  | $\bullet$ |  |
|  | 2 to 10 VDC |  |  | $\bullet$ | $\bullet$ |  |  |  |
|  | Variable (0 to 10 VDC) |  |  |  |  | - |  | $\bullet$ |
| Running Time | 150 seconds | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |  |
|  | 7 seconds |  |  |  |  |  | - | - |
| Wiring | Plenum Rated Cable | $\bullet$ |  | $\bullet$ |  | $\bullet$ | $\bullet$ | $\bullet$ |
|  | Appliance Cable |  | $\bullet$ |  | $\bullet$ |  |  |  |
|  | Conduit Fitting | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |

Installation and Operation... (page 265).
*Based on 4 in- $\mathrm{lb} / \mathrm{tt}^{2}$ damper torque loading. Parallel blade. No edge seals.

## A CLOSER LOOK...

- Brushless DC Motor for Added Accuracy and Controllability.
- Don't Worry about Actuator Burn-Out; Belimo is Overload Proof throughout Rotation.
- Enjoy Added Flexibility with Easy Mechanical Stops to Adjust Linear Movement.
- Need to Change Control Direction? Do it easily with a Simple Switch.
- Easily Accessible Manual Override Button helps you Pre-Tension Damper Blades.
- Standard 3ft Plenum Rated Cable and Conduit Connector Provided on Basic Models
- Added Flexibility to Select Clamp, Electrical Connection, and Running Time to fit your Specific Application with Belimo's New Flexible Line of Actuators.



## The Belimo Difference

- Customer Commitment.

Extensive product range. Application assistance.
Same-day shipments. Free technical support. Five year warranty.

- Low Installation and Life-Cycle Cost.

Easy installation. Accuracy and repeatability.
Low power consumption. No maintenance.

- Long Service Life.

Components tested before assembly. Every product tested before shipment.
$30+$ years direct coupled actuator design.


| Technical Data | AHB(X)24-3(-100)(-200)(-300) |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz} \\ & 24 \mathrm{VDC} \pm 20 \% \end{aligned}$ |
| Power consumption | 2 W (0.5 W) |
| Transformer sizing | 4.5 VA (Class 2 power source) |
| Electrical connection | 18 GA appliance rated cable 1/2" conduit connector protected NEMA 2 (IP54) $3 \mathrm{ft}[1 \mathrm{~m}] 10 \mathrm{ft}[3 \mathrm{~m}] 16 \mathrm{ft}[5 \mathrm{~m}]$ |
| Overload protection | electronic throughout full stroke |
| Control | on/off, floating point |
| Input impedance | $600 \Omega$ |
| Linear Stroke |  |
| AHB (X) 24-3-100 | 4 in [100 mm] |
| AHB (X) 24-3-200 | 8 in [200 mm] |
| AHB (X) 24-3-300 | 12 in [ 300 mm ] |
| Linear force | 101 lbf [450 N] |
| Stroke direction | reversible with $\downarrow / \uparrow$ switch |
| Manual override | external push button |
| Running time | 150 seconds per 4" |
| Humidity | 5 to 95\% RH non condensing (EN 60730-1) |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.80^{\circ} \mathrm{C}\right]$ |
| Housing | NEMA 2, IP54, UL enclosure type 2 |
| Housing material | UL94-5VA |
| Agency listings | cULus acc. to UL 60730-1A/-2-14, CAN/CSA E60730-1:02, <br> CE acc. to 2004/108/EEC and 2006/95/EC |
| Noise level (max) | 35 dB (A) |
| Servicing | maintenance free |
| Quality standard | ISO 9001 |
| Weight |  |
| AHB(X)24-3-100 | 2.6 lbs [ 1.18 kg ] |
| AHB(X)24-3-200 | 2.7 lbs [ 1.23 kg ] |
| AHB (X)24-3-300 | 2.9 lbs [ 1.32 kg ] |

Linear Force min. 101lbf for control of damper surfaces up to $\mathbf{3 2} \mathbf{~ s q}$. ft.

## Application

For on/off and floating point control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The $\operatorname{AHB}(X)$... series provides 4,8 , or 12 inches of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [20 mm] by means of the mechanical end stops.
When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.
The $\operatorname{AHB}(X) 24-3 .$. actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.


Accessories

| Z-DS1 | Rotary Support to Compensate Lateral Forces |
| :--- | :--- |
| Z-KSC | Linear Coupling |
| P370 | Shaft Mount Auxiliary Switch |

NOTE: When using $\operatorname{AHB}(\mathrm{X}) 24-3 \ldots$ actuators, only use accessories listed on this page.

## Typical Specification

Floating point, on/off control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators shall have brushless DC motor technology and be protected from overload at all positions of linear stroke. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cL Approved, have a 5-year warranty, and be manufactured under IS0 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

## X INSTALLATION NOTES

1Provide overload protection and disconnect as required.
$\qquad$ Actuators may also be powered by 24 VDC .

## 〔 application notes

- Meets cULLs or UL and CSA Standard requirements without the need of an electrical ground connection.


## WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical componests could result in death or serious injury.


On/Off control


Floating Point or On/Off control


| Technical Data | AHX120-3(-100)(-200)(-300) |
| :---: | :---: |
| Power supply | 100 to 240 VAC $50 / 60 \mathrm{~Hz}$ (nominal) 85 to 265 VAC $50 / 60 \mathrm{~Hz}$ (tolerance) |
| Power consumption | 2.5 W |
| Transformer sizing | 4.5 VA (Class 2 power source) |
| Electrical connection | 18 GA appliance rated cable 1/2" conduit connector protected NEMA 2 (IP54) 3 ft [ 1 m ] 10 ft [3m] 16 ft [5m] |
| Overload protection | electronic throughout full stroke |
| Control | on/off, floating point |
| Input impedance | $600 \Omega$ |
| Linear stroke |  |
| AHX120-3-100 | 4 in [100 mm] |
| AHX120-3-200 | 8 in [200 mm] |
| AHX120-3-300 | 12 in [ 300 mm ] |
| Linear force | $101 \mathrm{lbf}[450 \mathrm{~N}]$ |
| Stroke direction | reversible with $\downarrow / \uparrow$ switch |
| Manual override | external push button |
| Running time | 150 seconds per 4" |
| Humidity | 5 to 95\% RH non condensing (EN 60730-1) |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.80^{\circ} \mathrm{C}\right]$ |
| Housing | NEMA 2, IP54 |
| Housing material | UL94-5VA |
| Agency listings | cULus acc. to UL 60730-1A/-2-14, CAN/CSA C22.2 No. 24, CE according to \#74123IEEC |
| Noise level (max) | 35dB(A) |
| Servicing | maintenance free |
| Quality standard | ISO 9001 |
| Weight |  |
| AHX120-3-100 | 2.6 lbs [ 1.18 kg ] |
| AHX120-3-200 | 2.7 lbs [ 1.23 kg ] |
| AHX120-3-300 | 2.9 lbs [ 1.32 kg ] |

Linear Force min. 101lbf for control of damper surfaces up to $\mathbf{3 0} \mathbf{~ s q}$. ft.

## Application

For on/off and floating point control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The AHX... series provides 4, 8, or 12 inches of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [ 20 mm ] by means of the mechanical end stops.
When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.
The AHX120-3... actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.


| Accessories |  |
| :--- | :--- |
| Z-DS1 | Rotary Support to Compensate Lateral Forces |
| Z-KSC | Linear Coupling |
| KG6 | Ball Joint |
| KG8 | Ball Joint $\left(90^{\circ}\right.$ angle $)$ |
| KG10A | Ball Joint |
| P370 | Shaft Mount Auxiliary Switch |

NOTE: When using AHX120-3... actuators, only use accessories listed on this page.

## Typical Specification

Floating point, on/off control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators shall have brushless DC motor technology and be protected from overload at all positions of linear stroke. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cUL Approved, have a 5-year warranty, and be manufactured under IS0 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

## T installation notes

Provide overload protection and disconnect as required.
3 Actuators may also be powered by 24 VDC.

## < $\downarrow$ application notes

Meets cULus or UL and CSA Standard requirements without the need of an electrical ground connection.

## WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.


On/Off control



| Technical Data | AHB(X)24-SR(-100)(-200) |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz} \\ & 24 \mathrm{VDC} \pm 20 \% \end{aligned}$ |
| Power consumption | 2.5 W (0.5 W) |
| Transformer sizing | 4.5 VA (Class 2 power source) |
| Electrical connection | 18 GA plenum rated cable <br> 1/2" conduit connector <br> protected NEMA 2 (IP54) <br> $3 \mathrm{ft}[1 \mathrm{~m}] 10 \mathrm{ft}[3 \mathrm{~m}] 16 \mathrm{ft}[5 \mathrm{~m}]$ |
| Overload protection | electronic throughout full stroke |
| Control | 2 to 10 VDC, 4 to 20 mA |
| Input impedance | $100 \mathrm{k} \Omega(0.1 \mathrm{~mA}), 500 \Omega$ |
| Feedback output U | 2 to 10 VDC (max 0.5 mA$)$ |
| Linear stroke $\begin{aligned} & \text { AHB }(X) 24-S R-100 \\ & \text { AHB }(X) 24-S R-200 \end{aligned}$ | $\frac{4}{} \mathrm{in}[100 \mathrm{~mm}]$ |
| Linear force | $101 \mathrm{lbf}[450 \mathrm{~N}]$ |
| Stroke direction | reversible with $\downarrow / \uparrow$ switch actuator will move in the selected direction with increasing control signal (2 to 10V) |
| Manual override | external push button |
| Running time | 150 seconds per 4"  variable |
| Humidity | 5 to 95\% RH non condensing (EN 60730-1) |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176{ }^{\circ} \mathrm{F}$ [ $40^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ ] |
| Housing | NEMA 2, IP54, UL enclosure type 2 |
| Housing material | UL94-5VA |
| Agency listings | cULus acc. to UL 60730-1A/-2-14, CAN/CSA E60730-1:02, <br> CE acc. to 2004/108/EEC and 2006/95/EC |
| Noise level (max) | 35 dB (A) |
| Servicing | maintenance free |
| Quality standard | IS0 9001 |
| Weight |  |
| AHB(X)24-SR-100 | 2.6 lbs [1.78 kg] |
| AHB(X)24-SR-200 | 2.7 lbs [1.23 kg] |

Force $\mathbf{m i n} .101 \mathrm{lbf}$ for control of damper surfaces up to $\mathbf{3 2} \mathbf{~ s q}$. ft.

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator operates in response to a 2 to 10 VDC, or with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The $A H B(X) 24$ series provides 4 or 8 inches of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [20 mm ] by means of the mechanical end stops.

The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [20 mm ] by means of the mechanical end stops.
When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The AHB (X)24-SR... actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.


| Accessories |  |
| :--- | :--- |
| Z-DS1 | Rotary Support to Compensate Lateral Forces |
| Z-KSC | Linear Coupling |
| P370 | Shaft Mount Auxiliary Switch |
| SGA24 | Min Positioners in NEMA 4 Housing |
| SGF24 | Min Positioners for Flush Panel Mounting |
| PTA-250 | Pulse Width Modulation Interface |
| IRM-100 | Input Rescaling Module |
| ADS-100 | Analog to Digital Switch |
| ZG-R01 | Resistor for 4 to 20 mA Conversion |
| NSV24 US | Battery Back-Up Module |
| ZG-X40 | Transformer |
| NOTE: When using AHB(X)24-SR... actuators, only use accessories listed on this page. |  |

## Typical Specification

Proportional control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cL Approved, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

## X INSTALLATION NOTES

Provide overload protection and disconnect as required.

## CAUTION Equipment Damage!

Actuators may be connected in parallel. Power consumption and input impedance must be observed.


Actuators may also be powered by 24 VDC .
Only connect common to neg. (-) leg of control circuits.

## - APPLICATION NOTES

The ZG-R01 $500 \Omega$ resistor converts the 4 to 20 mA control signal to 2 to 10 VDC , up to 2 actuators may be connected in parallel.

WARNING Live Electrical Components!
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical componets could result in death or serious injury.


Proportional, 2 to 10 VDC control


Proportional, 4 to 20 mA control

Proportional, Non-Spring Return, Linear Stroke, 120 V, for 2 to 10 VDC or 4 to 20 mA


| Technical Data | AHB (X)120-SR(-100)(-200) |
| :---: | :---: |
| Power supply | 100 to 240 VAC $50 / 60 \mathrm{~Hz}$ (nominal) 85 to $265 \mathrm{VAC} 50 / 60 \mathrm{~Hz}$ (tolerance) |
| Power consumption | 5 W (1.2 W) |
| Transformer sizing | 7.5 VA (Class 2 power source) |
| Electrical connection | 18 GA appliance rated cable <br> 1/2" conduit connector protected NEMA 2 (IP54) <br> $3 \mathrm{ft}[1 \mathrm{~m}] 10 \mathrm{ft}[3 \mathrm{~m}] 16 \mathrm{ft}[5 \mathrm{~m}]$ |
| Overload protection | electronic throughout full stroke |
| Control | 2 to $10 \mathrm{VDC}, 4$ to 20 mA |
| Input impedance | $100 \mathrm{k} \Omega(0.1 \mathrm{~mA}), 500 \Omega$ |
| Feedback output U | 2 to 10 VDC (max 0.5 mA$)$ |
| Linear stroke AHX120-SR-100 AHX120-SR-200 | $4 \text { in [100 mm] }$ |
| Linear force | $101 \mathrm{lbf}[450 \mathrm{~N}]$ |
| Stroke direction | reversible with $\downarrow / \uparrow$ switch actuator will move in the selected direction with increasing control signal (2 to 10V) |
| Manual override | external push button |
| Running time | 150 seconds per 4"  variable |
| Humidity | 5 to 95\% RH non condensing (EN 60730-1) |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}$ [ $-40^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ ] |
| Housing | NEMA 2, IP54, UL enclosure type 2 |
| Housing material | UL94-5VA |
| Agency listings | cULus acc. to UL 60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EEC and 2006/95/EC |
| Noise level (max) | 35 dB (A) |
| Servicing | maintenance free |
| Quality standard | ISO 9001 |
| Weight |  |
| AHX120-SR-100 | 2.6 lbs [ 1.18 kg ] |
| AHX120-SR-200 | 2.7 lbs [ 1.23 kg ] |

Force min. 101 lbf for control of damper surfaces up to 32 sq . ft.

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator operates in response to a 2 to 10 VDC , or with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication or master-slave applications.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The AHX120 series provides 4 or 8 inches of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [ 20 mm ] by means of the mechanical end stops.
The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [20 mm ] by means of the mechanical end stops.

When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The AHX120-SR... actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.


| Accessories | Rotary Support to Compensate Lateral Forces |
| :--- | :--- |
| Z-DS1 | Linear Coupling |
| Z-KSA | Shaft Mount Auxiliary Switch |
| P370 | Min Positioners in NEMA 4 Housing |
| SGA24 | Min Positioners for Flush Panel Mounting |
| SGF24 | Pulse Width Modulation Interface |
| PTA-250 | Input Rescaling Module |
| IRM-100 | Analog to Digital Switch |
| ADS-100 | Resistor for 4 to 20 mA Conversion |
| ZG-R01 | Battery Back-Up Module |
| NSV24 US | Transformer |
| ZG-X40 |  |

## Typical Specification

Proportional control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cUL Approved, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagram

$\underset{\sim}{ }$ installation notes
Provide overload protection and disconnect as required.
CAUTION Equipment Damage!
Actuators may be connected in parallel.
Power consumption and input impedance must be observed.
Only connect common to neg. (-) leg of control circuits.

## APPLICATION NOTES

A The ZG-R01 $500 \Omega$ resistor converts the 4 to 20 mA control signal to 2 to 10 VDC , up to 2 actuators may be connected in parallel.

WARNING Live Electrical Components!
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.


2 to 10 VDC and 4 to 20 mA control

Proportional, Non-Spring Return, Linear Stroke, 24 V, Multi-Function Technology ${ }^{\circledR}$


Linear Force min. 101 lbf for control of damper surfaces up to $\mathbf{3 2}$ sq. ft.

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The default parameters for 2 to 10 VDC applications of the ...MFT actuator are assigned during manufacturing. If necessary, custom versions of the actuators can be ordered. The parameters can be changed by two means: pre-set and custom configurations from Belimo or on-site configurations using the Belimo PC-Tool software.

## Operation

The actuator is not provided with and does not require and limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.
The AHX series provides 4,8 , or 12 inches of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [ 20 mm ] by means of the mechanical end stops.

When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.
The AHX24-MFT... actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.


AHX24-MFT(-100)(-200)(-300)
Proportional, Non-Spring Return, Linear Stroke, 24 V, Multi-Function Technology ${ }^{\circledR}$

| Accessories | Rotary Support to Compensate Lateral Forces |
| :--- | :--- |
| Z-DS1 | Linear Coupling |
| Z-KSC | Shaft Mount Auxiliary Switch |
| P370 | Min Positioners in NEMA 4 Housing |
| SGA24 | Min Positioners for Flush Panel Mounting |
| SGF24 | Pulse Width Modulation Interface |
| PTA-250 | Input Rescaling Module |
| IRM-100 | Analog to Digital Switch |
| ADS-100 | Resistor for 4 to 20 mA Conversion |
| ZG-R01 | Battery Back-Up Module |
| NSV24 US | Transformer |
| ZG-X40 |  |

## Typical Specification

Proportional control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators must provide control in response to a control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5 -year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

## X installation notes

Provide overload protection and disconnect as required.

## CAUTION Equipment Damage!

Actuators may be connected in parallel if not mechanically mounted to the same shaft. Power consumption and input impedance must be observed.
Actuators may also be powered by 24 VDC .
Position feedback cannot be used with Triac sink controller.
The actuator internal common reference is not compatible.
Control signal may be pulsed from either the Hot (source)
or the Common (sink) 24 VAC line.
Contact closures A \& B also can be triacs.
$A \& B$ should both be closed for triac source and open for triac sink.
For triac sink the common connection from the actuator must be connected to the hot connection of the controller.
APPLICATION NOTES
The ZG-R01 $500 \Omega$ resistor may be used.

## WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.


On/Off control


Floating Point control


Linear Force min. 44 Ibf for control of damper surfaces up to 12 sq . ft.

## Application

For On/Off control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

## Operation

The actuator is not provided with and does not require and limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.
The $\operatorname{AHQB}(X)$ series provides 4 " 100 mm ] of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of $0.8^{\prime \prime}$ [ 20 mm ] by means of the mechanical end stops.
When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.
The AHQB (X)24-1-100 actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.


| Accessories |  |
| :--- | :--- |
| Z-DS1 | Rotary Support to Compensate Lateral Forces |
| Z-KSC | Linear Coupling |
| P370 | Shaft Mount Auxiliary Switch |

NOTE: When using $\operatorname{AHQB}(\mathrm{X}) 24-1-100$ actuators, only use accessories listed on this page.

## Typical Specification

On/Off control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators shall have brushless DC motor technology and be protected from overload at all positions of linear stroke. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cOL listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagram

## $\nless$ installation notes

AProvide overload protection and disconnect as required. Actuators may also be powered by 24 VC.

## 4 APPLICATION NOTES

- Meets cULLs or UL and CSA Standard requirements without the need of an electrical ground connection.

1 WARNING Live Electrical Components!
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical componets could result in death or serious injury.


On/Off control

## AHQB(X)24-MFT-100

Proportional, Non-Spring Return, Linear Stroke, 24 V, Multi-Function Technology ${ }^{\circledR}$


Linear Force min. 44 Ibf for control of damper surfaces up to 12 sq . ft.

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The default parameters for 2 to 10 VDC applications of the ...MFT actuator are assigned during manufacturing. If necessary, custom versions of the actuators can be ordered. The parameters can be changed by two means: pre-set and custom configurations from Belimo or on-site configurations using the Belimo PC-Tool software.

## Operation

The actuator is not provided with and does not require and limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The AHQB( ) series provides 4 " [100 mm] of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 " [ 20 mm ] by means of the mechanical end stops.

When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The AHQB(X)24-MFT-100 actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

| Technical Data | AHQB(X)24-MFT-100 |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz} \\ & 24 \mathrm{VDC} \pm 20 \% \end{aligned}$ |
| Power consumption | 13 W (1.5 W) |
| Transformer sizing | 23 VA (Class 2 power source) |
| Electrical connection AHQB24-MFT-100 | 3 ft [1m] <br> 18 GA plenum rated cable protected NEMA 2 (IP54) |
| AHQX24-MFT-100 | 3 ft [ 1 m ] 10 ft [3m] $16 \mathrm{ft}[5 \mathrm{~m}]$ 18 GA plenum rated cable protected NEMA 2 (IP54) |
| Overload protection | electronic throughout full stroke |
| Control | 2 to 10 VDC, 4 to 20 mA (default) Variable (VDC, on/off) |
| Input impedance | $100 \mathrm{k} \Omega$ ( 0.1 mA ), $500 \Omega, 1000 \Omega$ (0n/off) |
| Feedback output U | 2 to $10 \mathrm{VDC}, 0.5 \mathrm{~mA} \mathrm{max}$, VDC variable |
| Linear stroke | 1.6 " to 4.0 " [ 40 mm to 100 mm ] |
| Linear force | 44 lbf [200 Nm] |
| Stroke direction | reversible with $\downarrow / \uparrow$ switch |
| Manual override | external push button |
| Running time | 7 seconds per 4"  variable (7, 10, 15 or 35 seconds) |
| Humidity | 5 to 95\% RH non condensing (EN 60730-1) |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.80^{\circ} \mathrm{C}\right]$ |
| Housing | NEMA 2, IP54, UL enclosure type 2 |
| Housing material | UL94-5VA |
| Agency listings | cULus acc. to UL 60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EEC and 2006/95/EC |
| Noise level (max) | $<52 \mathrm{~dB}(\mathrm{~A})$ |
| Servicing | maintenance free |
| Quality standard | IS0 9001 |
| Weight | 2.7 lbs [ 1.23 kg ] |



| Accessories | Rotary Support to Compensate Lateral Forces |
| :--- | :--- |
| Z-DS1 | Linear Coupling |
| Z-KSC | Shaft Mount Auxiliary Switch |
| P370 | Min Positioners in NEMA 4 Housing |
| SGA24 | Min Positioners for Flush Panel Mounting |
| SGF24 | Pulse Width Modulation Interface |
| PTA-250 | Input Rescaling Module |
| IRM-100 | Analog to Digital Switch |
| ADS-100 | Resistor for 4 to 20 mA Conversion |
| ZG-R01 | Battery Back-Up Module |
| NSV24 US | Transformer |
| ZG-X40 | NOTE: When using AHOB(X)24-MFT-100 actuators, only use accessories listed on this page. |

## Typical Specification

Proportional control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators must provide control in response to a control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

> installation notes
Provide overload protection and disconnect as required.
CAUTION Equipment Damage!
Actuators may be connected in parallel if not mechanically mounted to the same shaft. Power consumption and input impedance must be observed.
Actuators may also be powered by 24 VDC .
Control signal may be pulsed from either the Hot (source) or the Common (sink) 24 VAC line.

## \& APPLICATION NOTES

The ZG-R01 $500 \Omega$ resistor may be used.

## WARNING Live Electrical Components!

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VDC/4-20 mA


On/Off control

